

DATA ANALYSIS

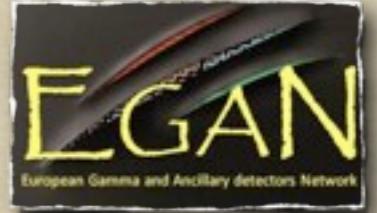
EGAN Workshop, Liverpool, December 5-9, 2011



Q. Stęzowski



Goals



- *Get a general (clear) view of what means
AGATA data analysis / data processing*
- *Be able to play with data*
- *Be able to become an actor*

Overviews

Basic elements



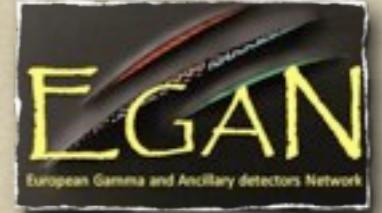
What already exists



How to extend



Overviews



Complexity

Basic elements

Narval philosophy

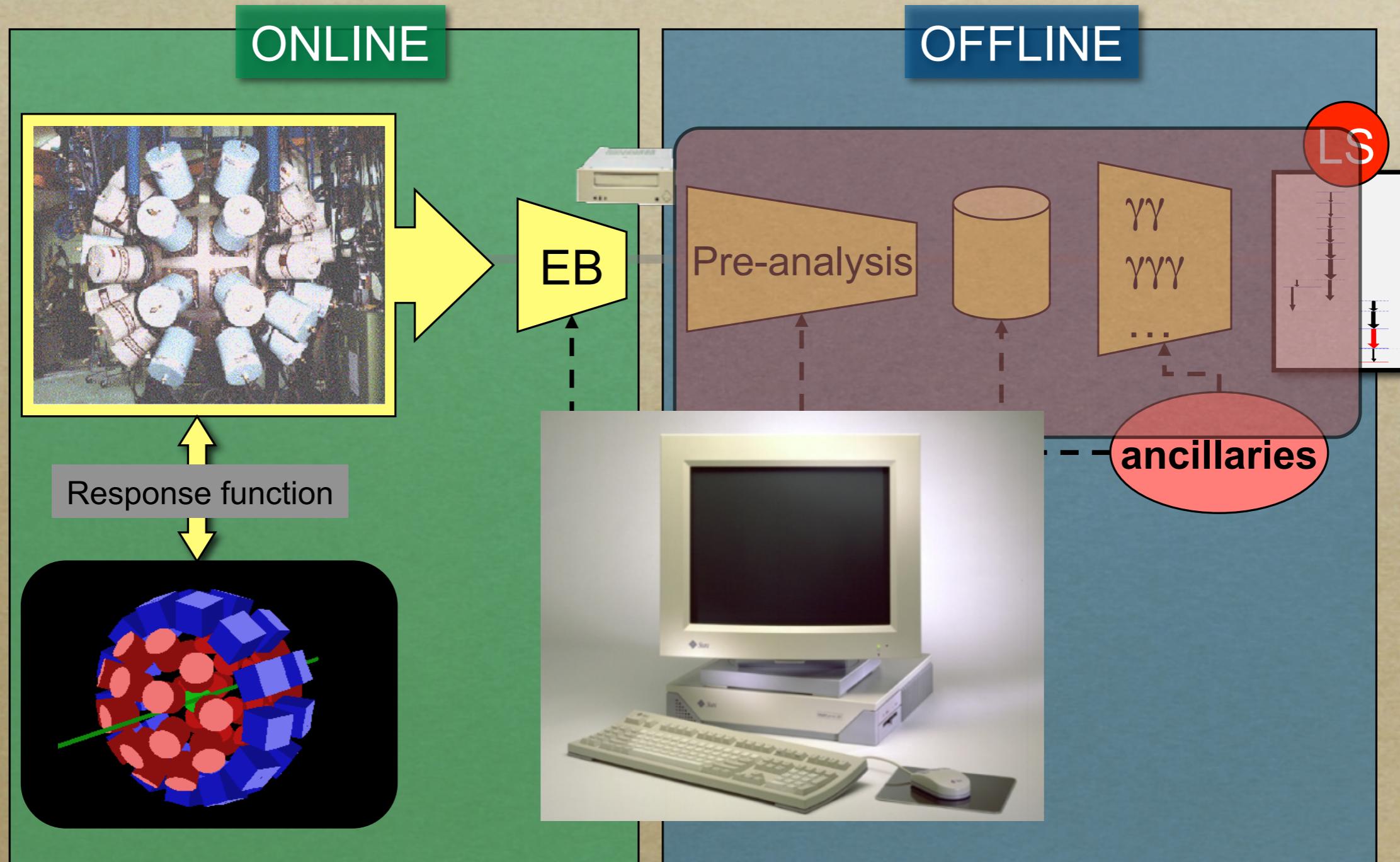
Organisation



Complex environment

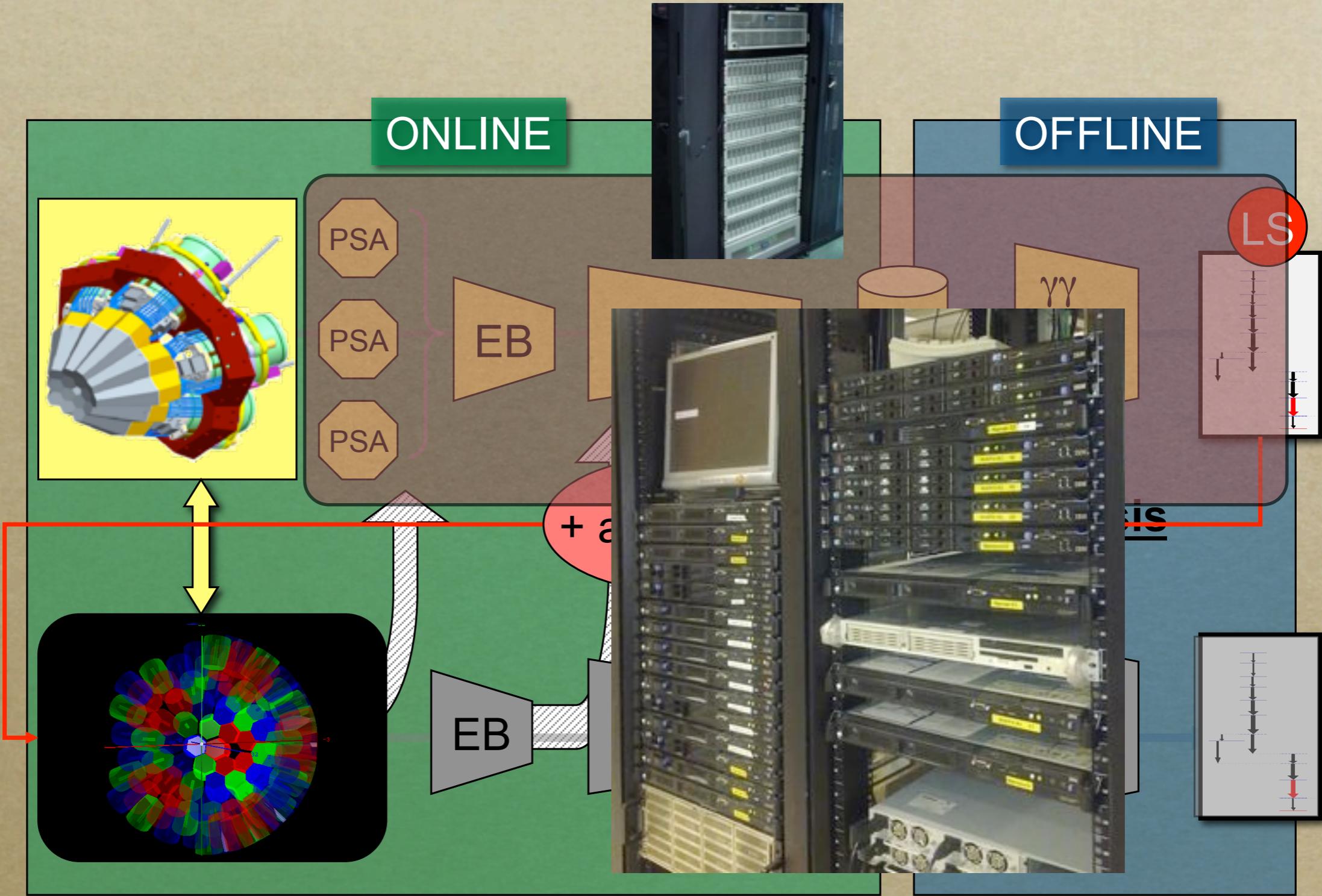


Illustration : my thesis



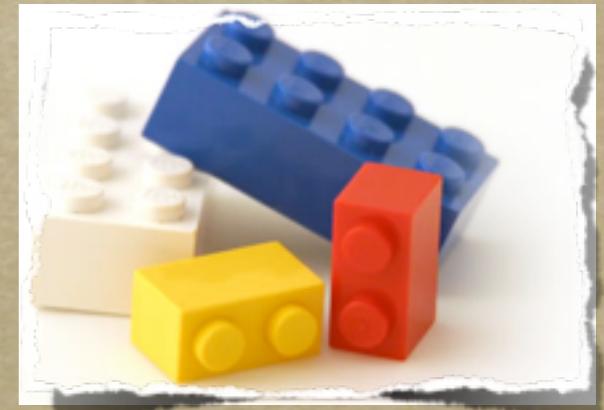


Complex environment



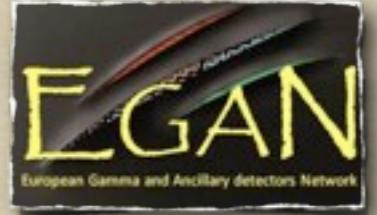
Complex environment

- many ‘builders’ involved in software
(building software packages is like building a bridge)
- need of coordinations
*shared files, doc (user’s guide, code), tutorial, bugtracker, elog ...
[model : G4, ROOT]*
- different roles :
 - ↳ users : use the existing bricks
 - ↳ developers : create new bricks
- several packages to be assembled
*interfaces between different parts
dependencies (compatibilities between the different parts)*





Complex environment



Narval

Femul

Root

Emulators

ISMA

ADF

Boost

ADPD

GammaWare

ADPL

How are they linked, dependent, used ???



Overviews



Complexity

Basic elements

Narval philosophy

Organisation



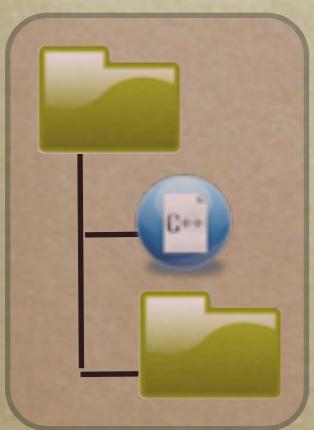
Work with SVN*



*subversion

Repository, on a server

can get any version, any time !



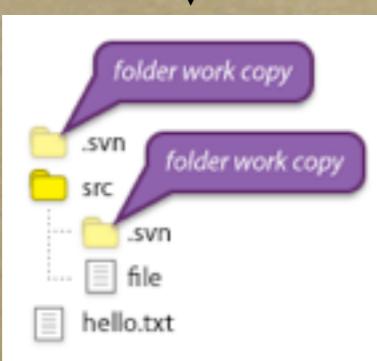
main development line : trunk

0

n



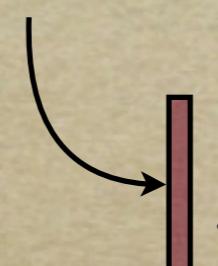
work on a local copy



....



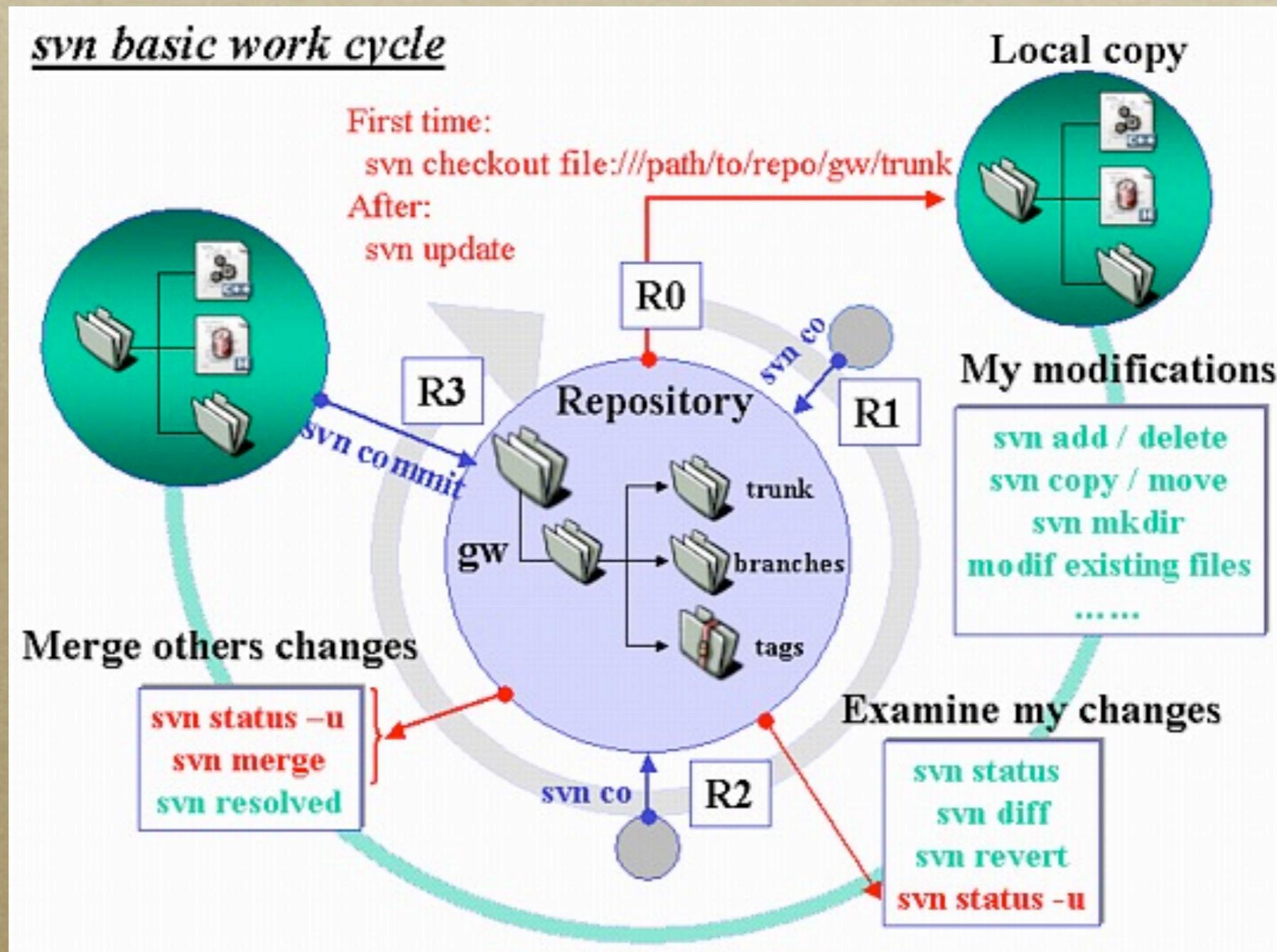
synchronize the local copy with
the repository



freezed : tag, release

Work with SVN*

**subversion*



svn cycle with the main commands



Work with SVN



[svn] / gammaware / trunk / src / adf / CrystalFrame.h

Repository: svn Go

Log of /gammaware/trunk/src/adf/CrystalFrame.h



Compare 1163 vs. Local — CrystalFrame.h

Debug | root5.24D_dev | x86_64 Overview Breakpoints Build and Debug Tasks Ungrouped Project

<No selected symbol> <No selected symbol>

```
#!/ to get individual segment
<*/
*virtual GeSegment *GetSegment(ushort_t) = 0;

//! to get each core
<*/
*virtual GeCore *GetCore(ushort_t) = 0;
};

//! General interface for a CrystalFrame
<*/
A crystal frame gives some global data, 36 segments signals and 2
*/
class ACrystalFrame : public AgataDataFrame<CrystalInterface>
{
protected:
    ACrystalFrame(const Key *akey):
        AgataDataFrame<CrystalInterface>(akey) {};
public:
    virtual ~ACrystalFrame()
    {};
};

// typedef ProxyDataFrame<ACrystalFrame, CrystalInterface> CrystalFrame;
} // namespace ADF
#endif
```

3 →

```
#!/ to get individual segment
<*/
*virtual GeSegment *GetSegment(ushort_t) = 0;

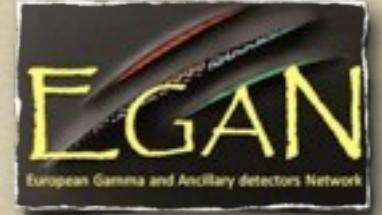
//! to get each core
<*/
*virtual GeCore *GetCore(ushort_t) = 0;
};

//! General interface for a CrystalFrame
<*/
A crystal frame gives some global data, 36 segments signals and 2
*/
class ACrystalFrame : public AgataDataFrame<CrystalInterface>
{
protected:
    ACrystalFrame(Key *akey):
        AgataDataFrame<CrystalInterface>(akey) {};
public:
    virtual ~ACrystalFrame()
    {};
};

// typedef ProxyDataFrame<ACrystalFrame, CrystalInterface> CrystalFrame;
} // namespace ADF
#endif
```



Work with SVN



- ① *Release versions: not that used ... so far (GSI ?)
lack of policy (root, any 6 months with objectives)
at least be aware of the version (release) you are using*
 - ② *Mercurial (Hg) also used @ GSI
(different but same philosophy)*
 - ③ *Good practice in case of problems/bugs, give :
the distribution (which linux, mac), environment
version of the codes, output etc ...*
- ☞ *not only : it does not work ...*





Main SVN servers



'narval emulator'

`svn://gamma01.lng.infn.it/agata/trunk/narval_emulator`

Orsay Forward Tracking

`http://csngwinfo.in2p3.fr:2401`

GammaWare

`svn+ssh://anonsvn@anonsvn.in2p3.fr`

→ *ADF*

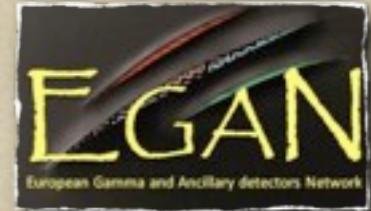
`svn+ssh://anonsvn@anonsvn.in2p3.fr/agata/gammaware/src/adf`

*python script
AgataLegnaro.py
to help
loading, compiling, installing
(see practical sessions)*

Questions : GSI, (GANIL), other Tracking, PSA ?



OTHERS useful sites



GammaWare Head Version for release 0.9

Search

Gw::Link
Gw::LoopControl
Gw::LoopOnTasks
Gw::LSaxis
Gw::MatPlayer
Gw::Measure< Data_T >
Gw::NuclearLevel
Gw::PadManager
Gw::Parity
Gw::Peak1D
Gw::PeakCreator
Gw::QNumber
Gw::RadLevelSchemeReader
Gw::RandObj
Gw::Random
Gw::RootSpectrumPlayer
Gw::Spin
Gw::StdHit
Gw::SymCorrelatedSpace
Gw::TestFeeding
Gw::TrackHit
Gw::TTreeBuilder

AutoSave
DoCanvas
Exec
GetLastSaveArg1
GetLastSaveArg2
GetLastSaveArg3
GetLastSaveArg4
LoopControl
Save
SetAutoTime
Zero
~LoopControl

```
void LoopControl::Save ( const Char_t * main,
                        const Char_t * tag,
                        const Char_t * option,
                        Int_t          autotime
                      )
```

Save the spectra in files.

- main_file is the name of the root file to save spectra
- tag_file is the name of the root file to save tagged spectra
- option has the following format :
 - ; means save spectra in the current TDirectory
 - (means open a new file
 -) means close the file
 - ch means works with a chain i.e. sequence of names with the same pattern.
 - option to Zero spectra is given using {opt1:opt2}.
- autotime : call automatically this command again after autotime seconds. Off if set to 0.

Here are some examples.

- if you have open your watcher is a root directory and would like just to save there the current histograms : "" "0" ";" 0
- to save in the current root dir, open a new one and move all histograms there : "my_new.root" "0" ";" 0
- to dump histograms in a root file (open, save and close the file) : "my_dump" "0" "();" 0
- to dump histograms in a chain of root files (open, save and close the file) : "my_dump" "0" "ch();" 0
it looks for existing my_dumpXXXX.root files in the current dir XXXX = [0, ...]. It takes the first non existing one.
- to open a new files that becomes the mother file of all watchers, and save histo there : "my_dump" "0" "();" 0
- to set spectra of the pool to zero : "my_dump" "0" "(); {pool}" 0
- to set all spectra to zero and change the binning : "my_dump" "0" "(); {pool:100 0 100}" 0

Definition at line 1046 of file Watchers.cpp.

Generated on Wed Nov 30 2011 02:05:25 for GammaWare by doxygen 1.7.4

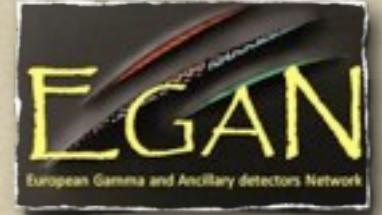
<http://www.ipm.in2p3.fr/gammaware/doc/html/html doc of the gw code>

<http://agata-0.lnl.infn.it:8989/>

*Fill it,
IMPORTANT*



Installation of the code



[*system/user*]

*required root privileges
apt-get, rpm, dmg etc ...*

*boost
skstream*



Grid, never admin

*(except if we are reached to buy a virtual box on each site)
sometime better to install on the user side*

For other AGATA packages, nothing like this

[*user*]

- *narval emulator : make, make install*
- *PRISMA : make, make install*
- *Gammaware : configure make, make install*
- *make install*
- *make install*

python script

AgataLegnaro.py

to help

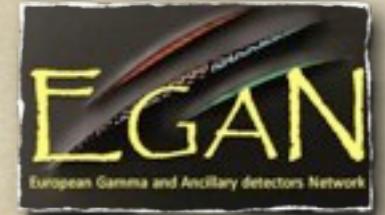
*loading, compiling, installing
(see practical sessions)*

*configure
make
make install*

Should be used widely in the future



Overviews



Complexity

Basic elements

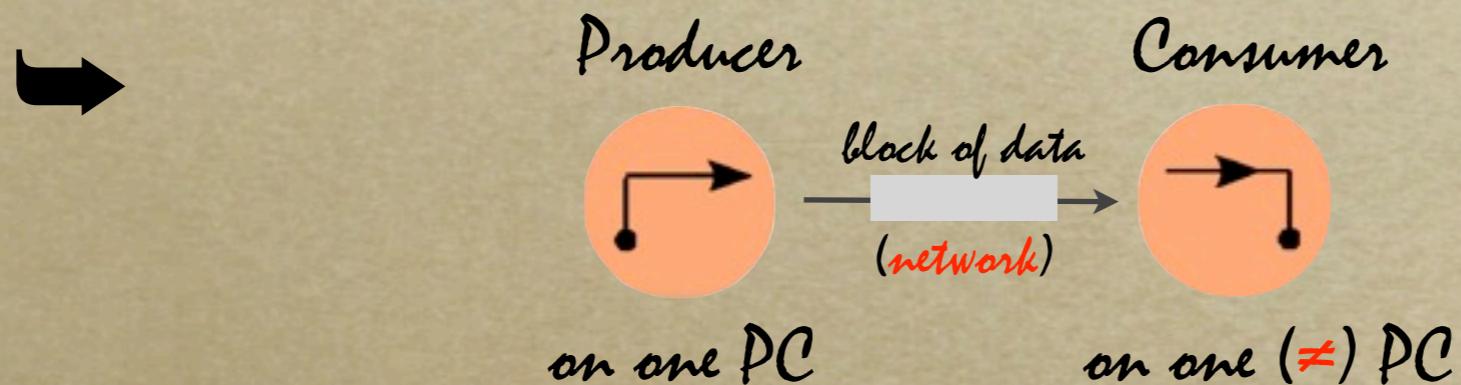
Narval philosophy

Organisation

Narval philosophy

Decomposition of processing in chain of actions

Ex - simple analysis : read data AND create spectra

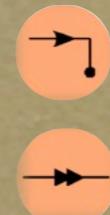


Advantages { if source of data changes, just change the producer
the same data flow could be redirected to different consumers

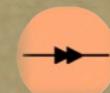
Main actors



Producer (produced data)



Consumer (consumer data)



Filter (consume data, apply algo, produce new data)

0 input, 1 output

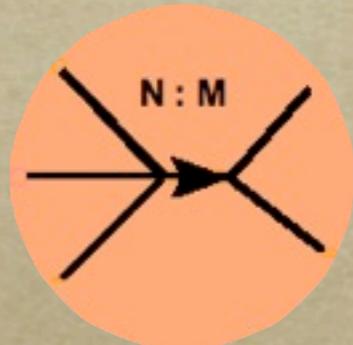
1 input, 0 output

1 input, 1 output

algorithms !
(tracking, PSA)

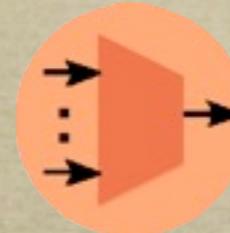
Narval philosophy

- ♣ More complex actors : organisation of the data flow



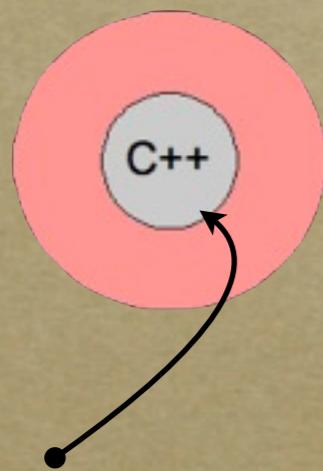
n inputs, m outputs

⇒ Event Builder, Merger i.e. *n inputs, 1 output*



- ♣ Narval is written in ADA BUT can load C/C++ code

⇒ the library has to define a precise interface^(*)



libActor.so

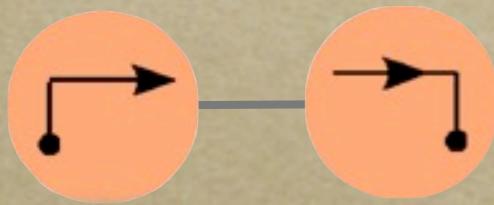
```
TrackingFilter *process_register (...)  
void process_config (...)  
void process_block(...)  
void process_initialise(...)  
void process_reset(...)  
void process_start(...)  
void process_stop(...)  
void process_pause(...)  
void process_resume(...)
```

⇒ only for producer, consumer and filter !

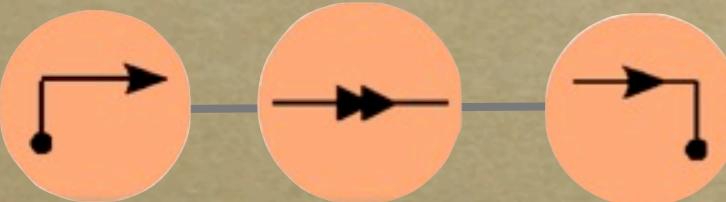
Narval philosophy

A topology defines how actors are connected.

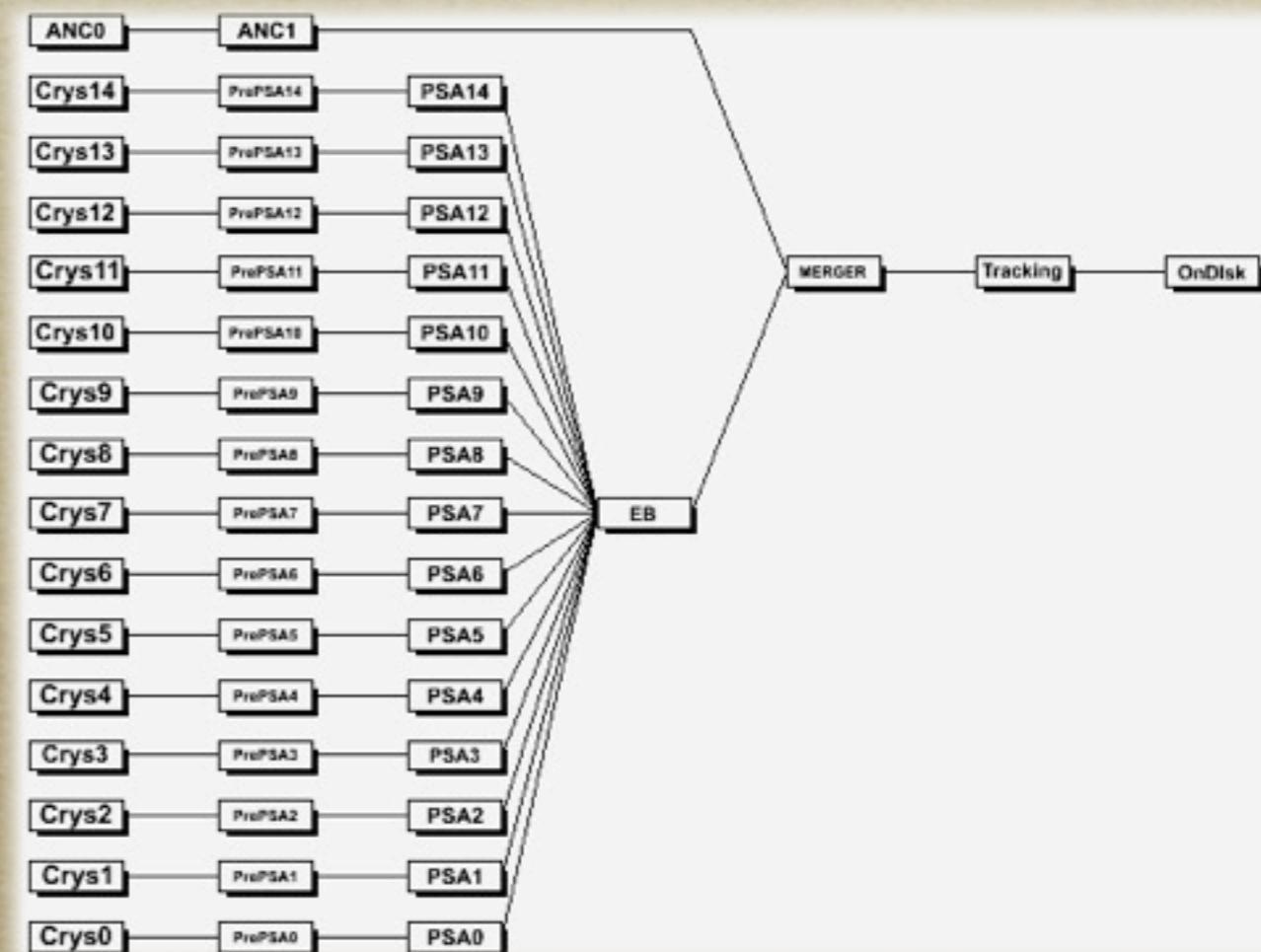
some examples



- read data, produce spectra
 - read data, produce root tree
- ...



- read data, apply filter, save
 - read data, apply algo, produce spectra
- ...



almost current online topology



Narval philosophy



Narval can :

- built complex topology
- run actors (ADA,C++) on clusters of PC

C++ actors can be assembled in C++ environment

- so-called emulators

Emulators are useful for :

- debugging
- developing new actor
- ‘light’ analysis ... i.e. does not required parallelisation

You can also install Narval in your institute !

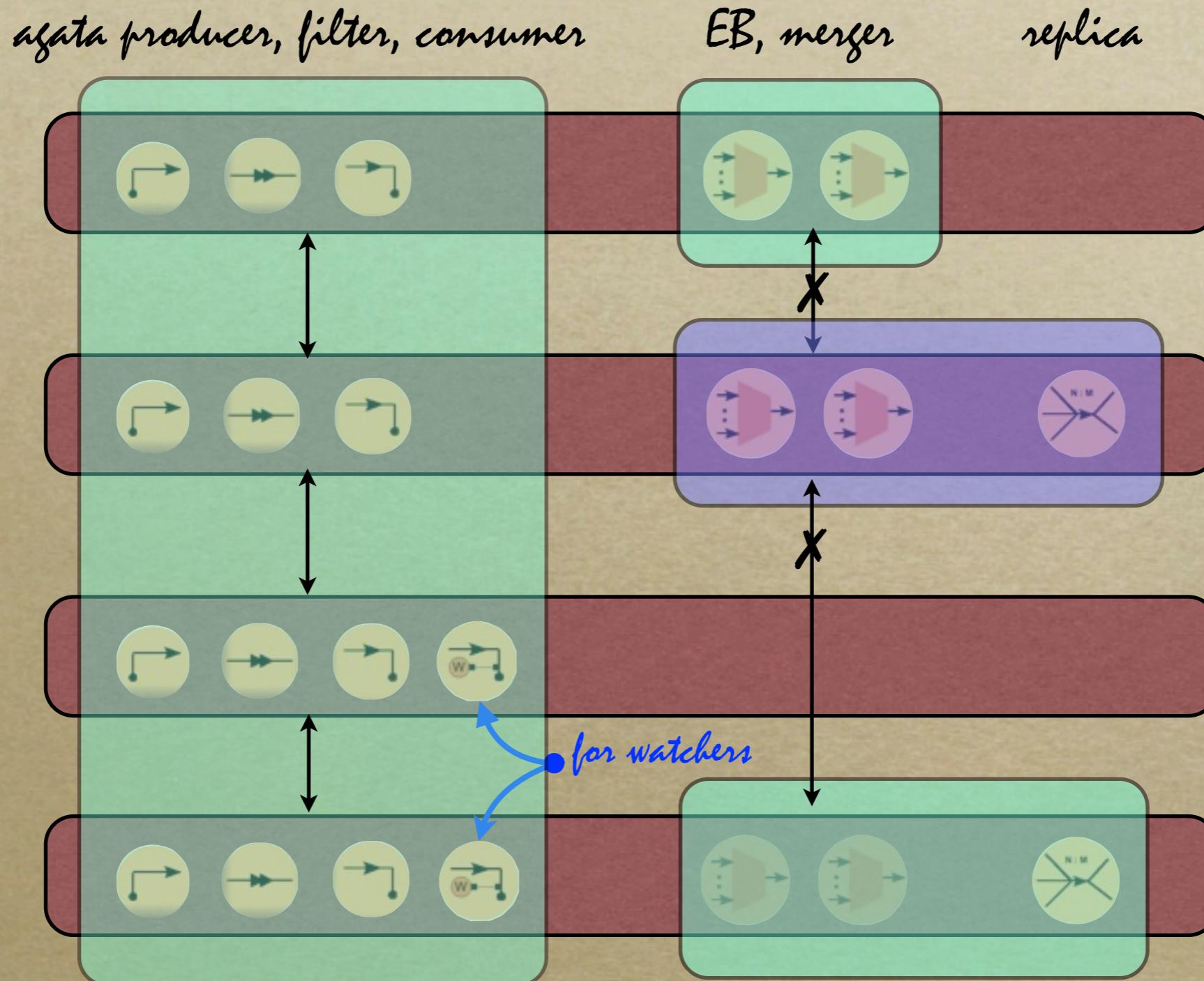
Actors in frameworks

femul
standalone exec

Narval
framework

ROOT_[Gw]
framework

ROOT_[Gw]
framework



c++

ada

EmulatorPC
EmulatorPFC

DEmulator
RMTEmulator ...
(BoostEmulator)
ProofEmulator ?



Agata shared actors



- The svn called ‘narval-emulator’ contains :*
- *the actors shared between the frameworks*
 - (BasicAFC, AncillaryProducerTCP, TrackingFilter PSAFilterGridSearch etc ...)
 - *the PRISMA library*
 - *femul + femul event builder / merger*
- + a copy of *ADF, OFT*
- *the actors shared between the frameworks*
 - Should be external packages ! (GSI?)
 - Otherwise pb of synchronisation

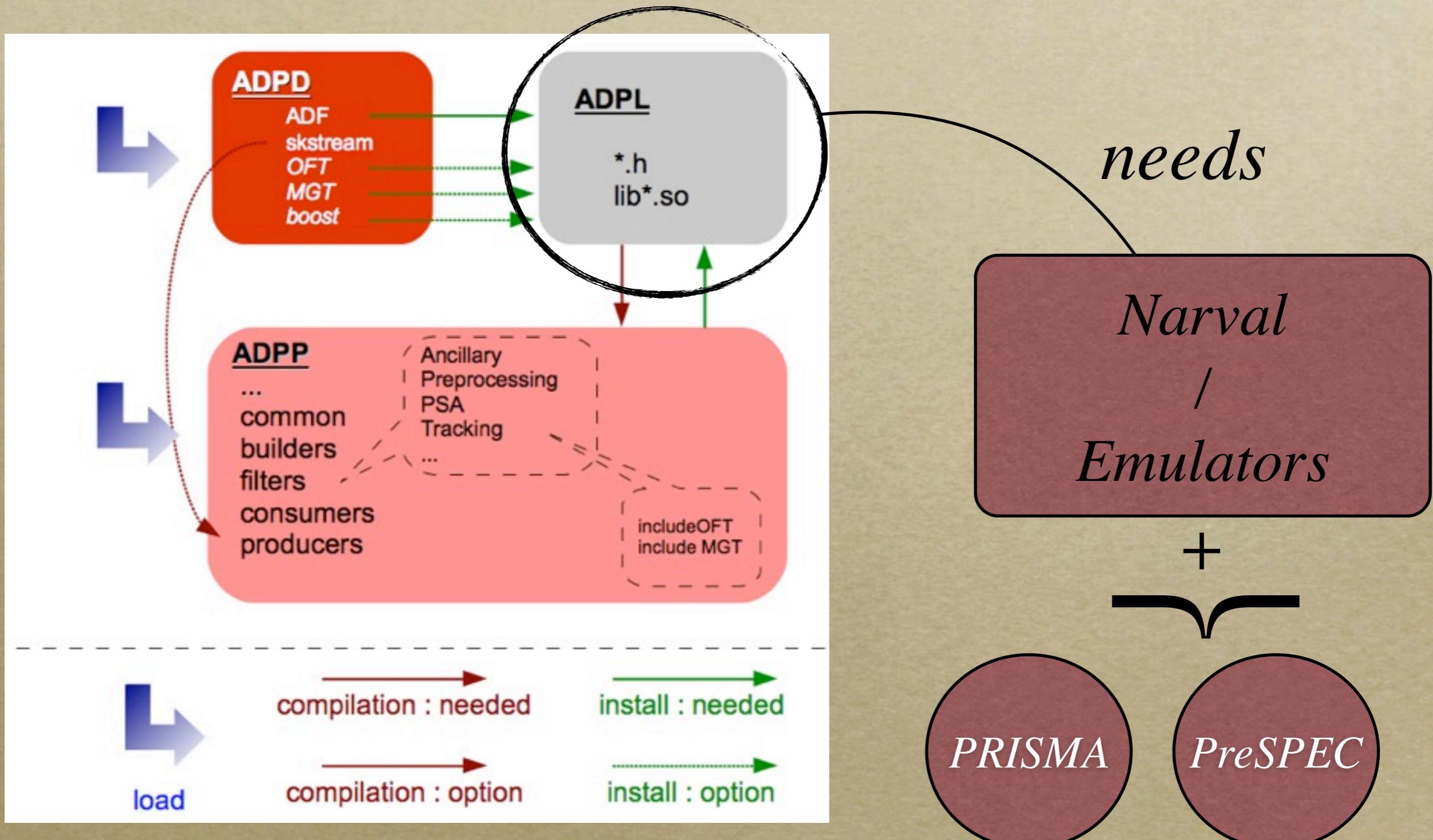
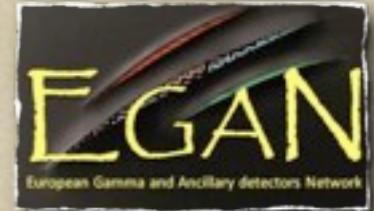
All libraries built in ADPL

Note : ADP is for Agata Data Processing

P for Package
D for Dependencies
L for Library

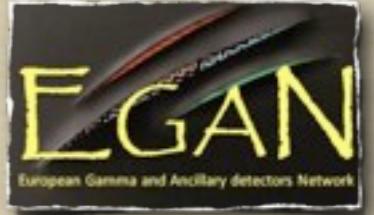


Agata shared actors





Complex environment



Narval

Femul

Root

Emulators

ISMA

ADF

Boost

ADPD

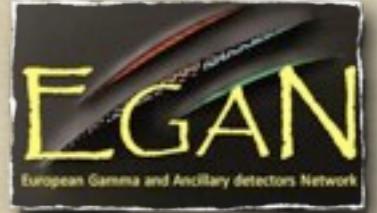
GammaWare

ADPL

I hope you have a better view of this !



Overviews



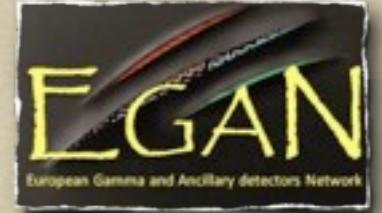
Basic elements

What already exists

How to extend



Overviews



Actor's actions

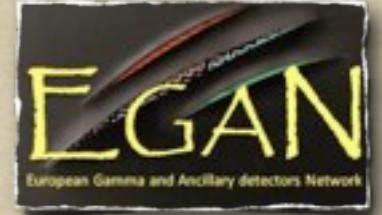
What already exists

Watchers

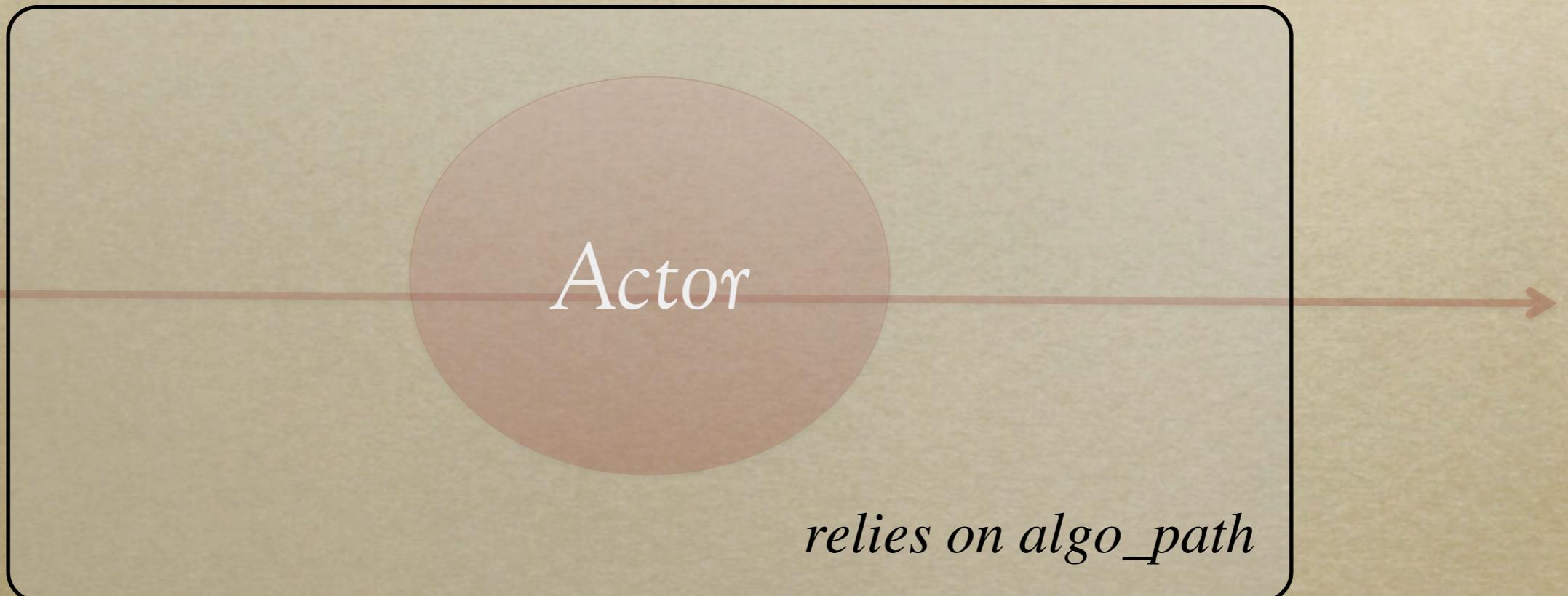
Data flow structure



Actor's communication



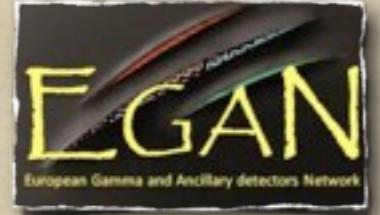
an actor is configured first ...



... means ~ the environment around is set



Actor's communication

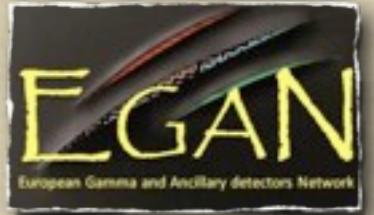


an actor is configured first ... then created

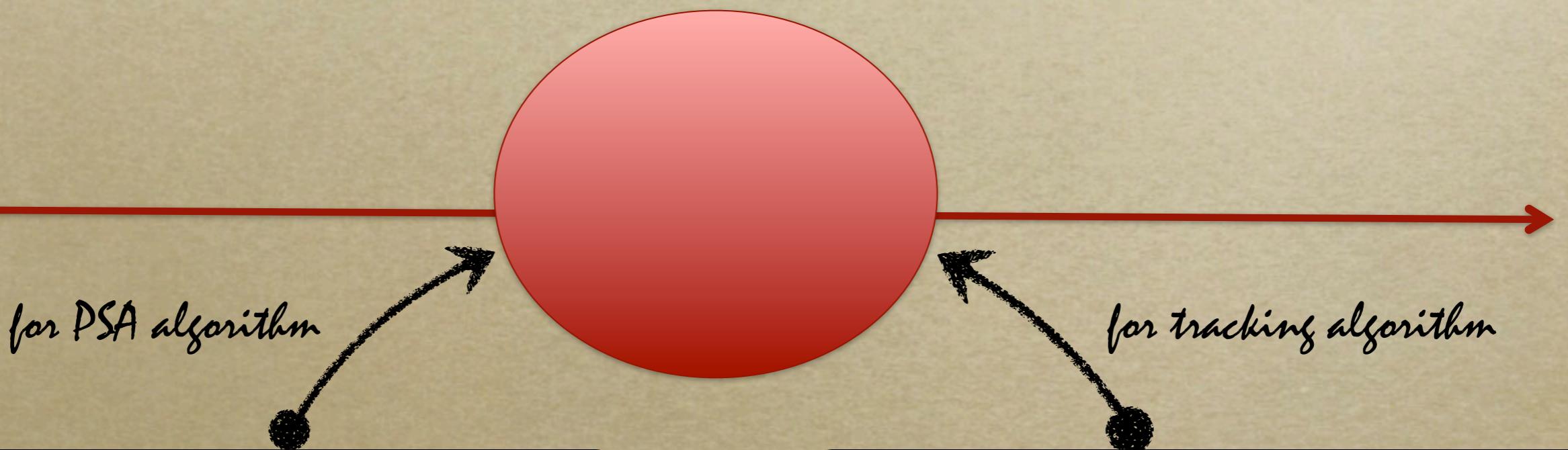




Actor's communication



the actor is initialised (just once) using .conf files



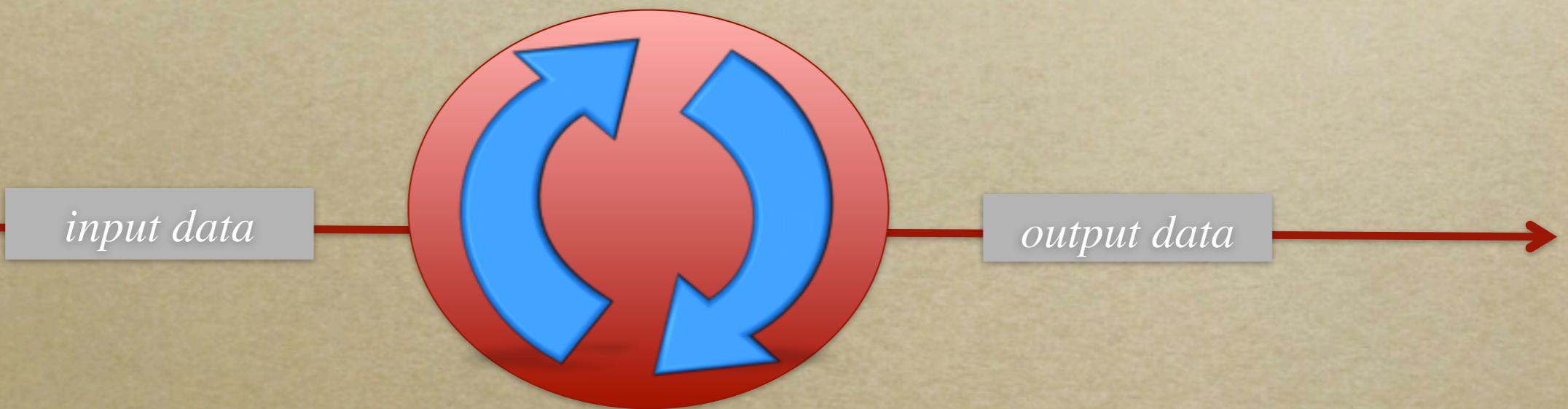
*ActualClass PSAFilterGridSearch
BasisFile /agatadisks/bases/ADL/LibTrap_C002.dat
SaveDataDir /agatadisks/data/2010_week24/Replay_run100/Out/1B
EnergyGain 2
WriteTraces 1000
XtalkFile xinv_1325-1340.cal*

*ActualClass TrackingFilterMGT
SaveDataDir /agatadisks/data/2010_week24/Replay_run100/Out/Global
EnergyGain 2
Ancillary
SourcePosition 0 0 -59
TimeWindowGeAnc 640 690
WriteInputHits*

Actor's communication



at running time ...



the actor

- extracts data from the input
- consumes them or not
- produces new data

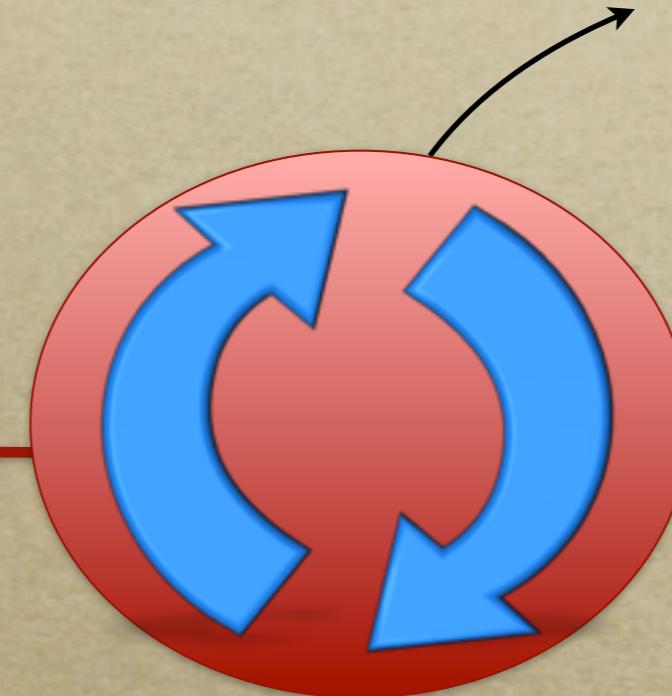
not only data can come from input
(ex : configuration frames)

Actor's communication



at running time ...

input data



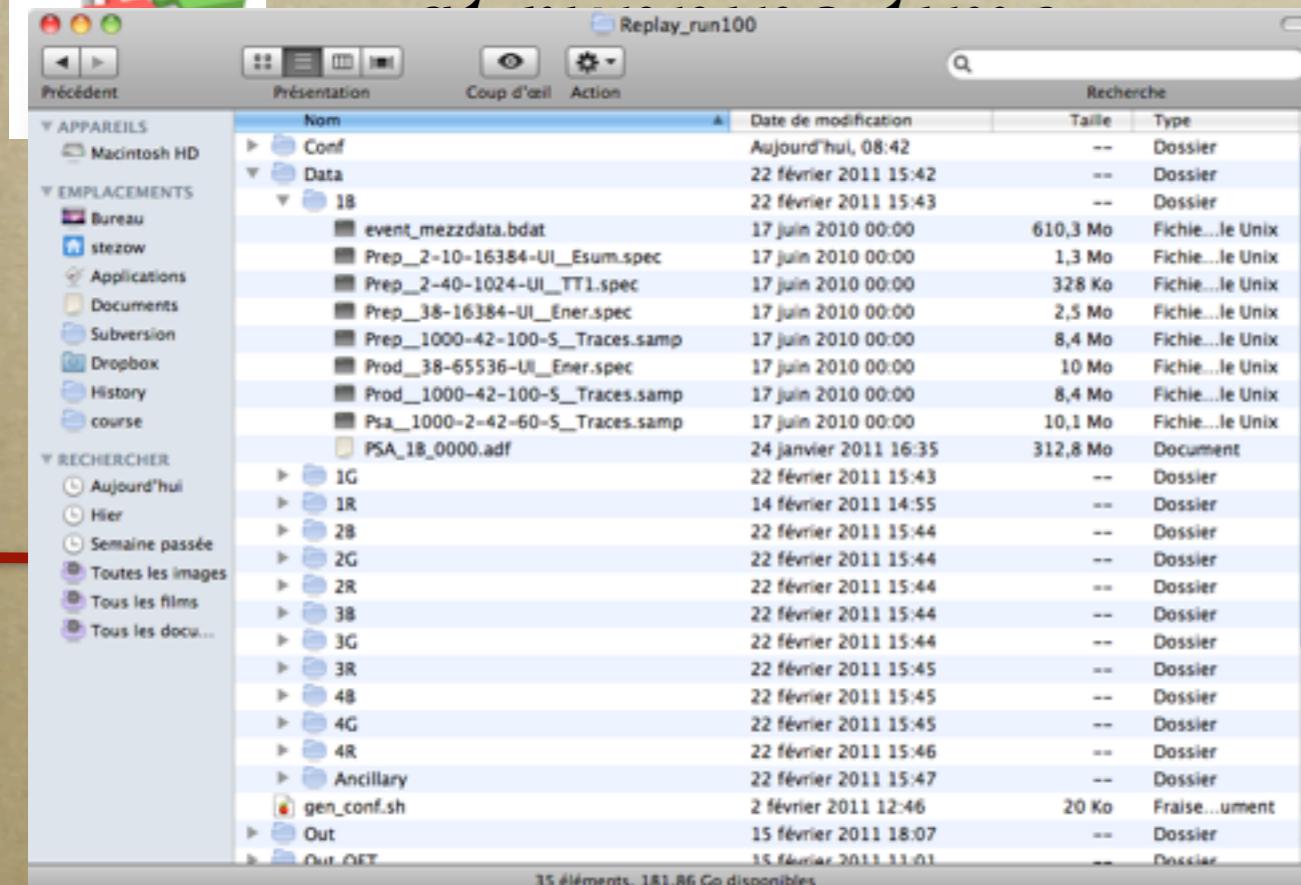
messages (printout, log system)

output data

the actor

- *sends messages*

Actor's communication



→ save spectra in files

SaveDataDir /agatadisks/data/2010_week24/Replay_run100/Out/1B

Prep_1000-42-100-S_Traces.samp
Prep_2-10-16384-UI_Esum.spec
Prep_2-40-1024-UI_TT1.spec
Prep_38-16384-UI_Ener.spec
Prod_1000-42-100-S_Traces.samp
Prod_38-65536-UI_Ener.spec
Psa_1000-2-42-60-S_Traces.samp

the actor

- produces spectra (if activated)

or spectra available with GRU

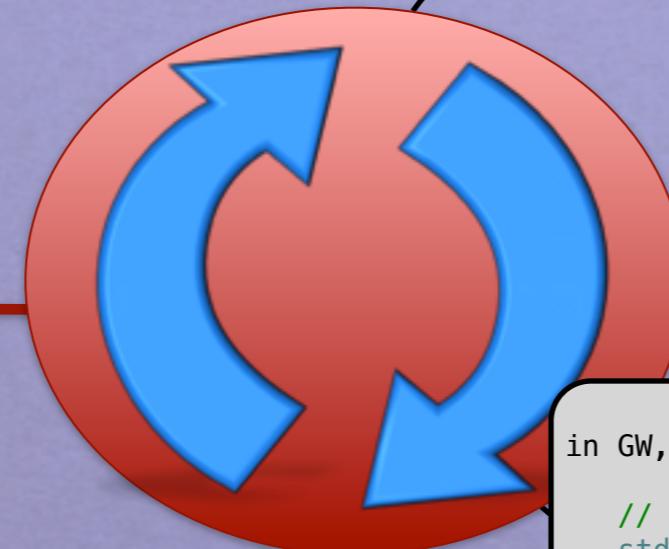
actor is a server of spectra
 ↗ machine, port #

Actor's communication



at running time ...

input data



Set/GetParameters()

Only in Naryal

GSI!

output data

the actor can

- have some parameters modified
- deliver copies of output from time to time

→ *Watchers*

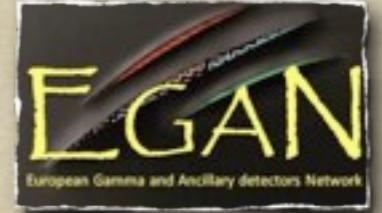
in GW, OnlineWatchers.C

```
// machine on which crystal producer is running
std::string gMachineCrys[gNumberOfCrystals] =
{
    "10.10.1.119", "10.10.1.113", "10.10.1.114",
    "10.10.1.115", "10.10.1.116", "10.10.1.117",
    "10.10.1.109", "10.10.1.110", "10.10.1.111",
    "10.10.1.106", "10.10.1.107", "10.10.1.108",
    "10.10.1.103", "10.10.1.104", "10.10.1.105"
};

UInt_t gPortCrys[gNumberOfCrystals] =
{
    9012, 9013, 9014,
    9015, 9016, 9017,
    9009, 9010, 9011,
    9006, 9007, 9008,
    9003, 9004, 9005
};
```



Overviews



Actor's actions

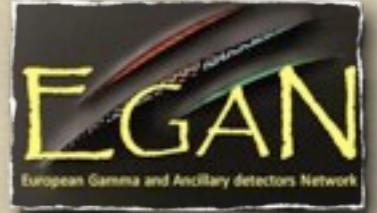
What already exists

Watchers

Data flow structure



Data flow structure



How look like the input and output buffers ?

→ **Basic element : Frame**

*A Frame is composed of a **key** and a **content***



*the key part give information
on the content*



*always starts with
frame length*



*mapping possible without
knowing the content*

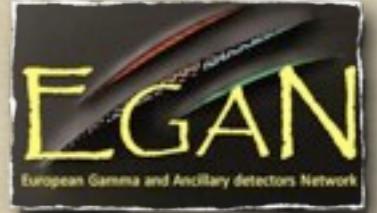
Agata key

length (4bytes) | type (4bytes) | event # (4 bytes) | TS (4bytes)

← →
20 bytes



Data flow structure



There are different kind of Frames

- data : produced (consumed by algo.) [binary]
- conf : to pass human readable info [ascii]
- meta : general data (ex: Vertex)

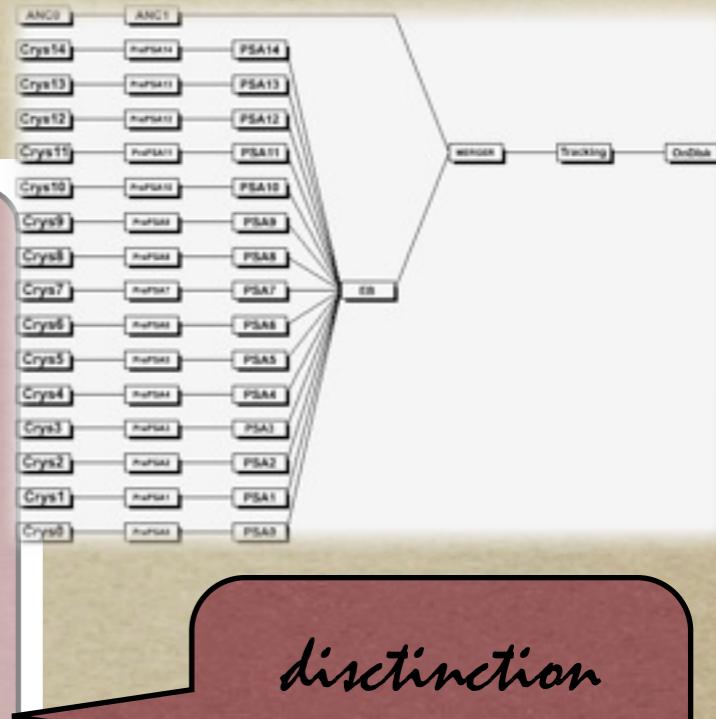
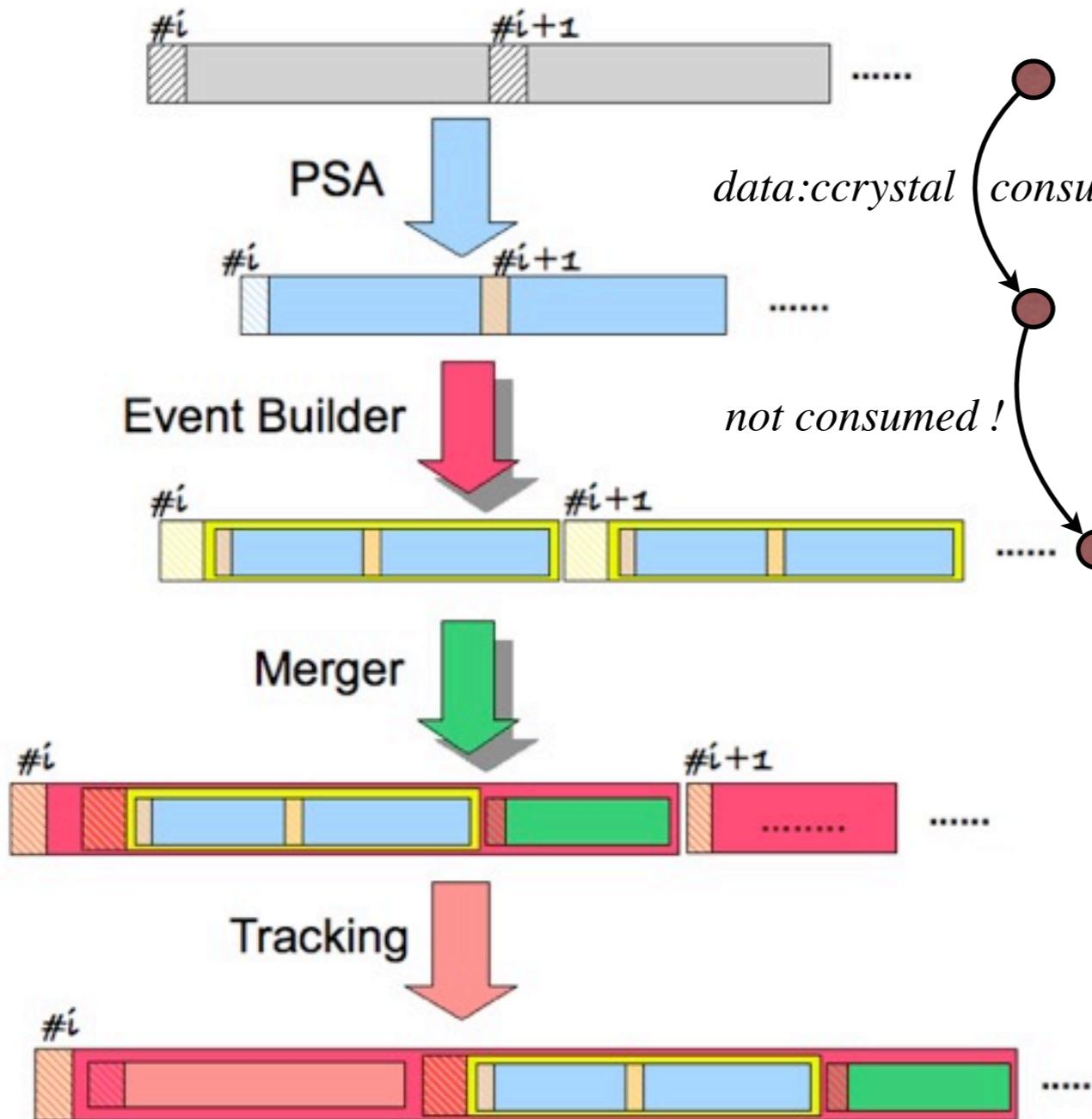
A Frame could be composed of Frames : CompositeFrame

→ coincidences ≈ event



Data flow structure

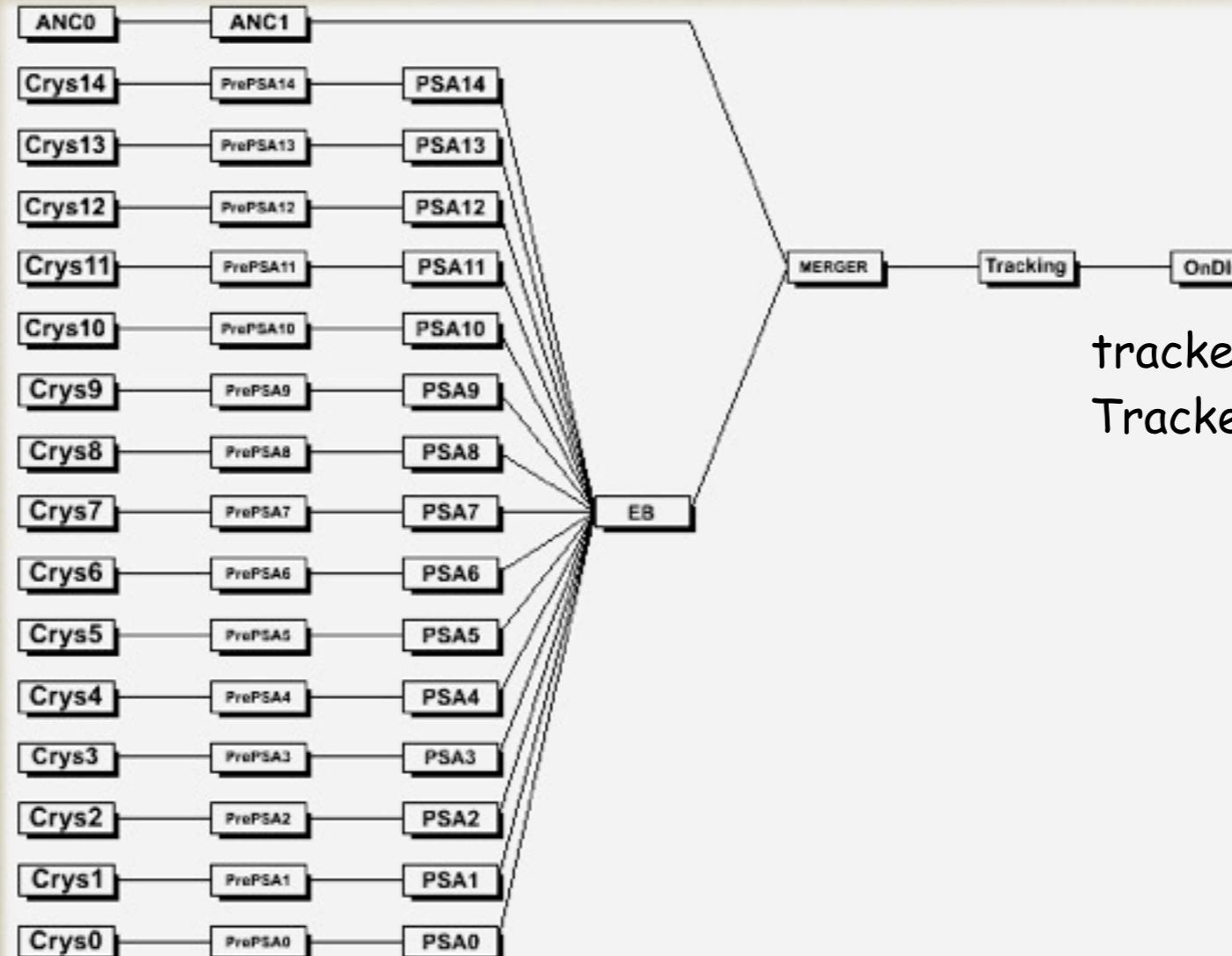
Frames currently in uses



*distinction
using Key[type]*

*to be defined
@ GSI*

Data flow structure

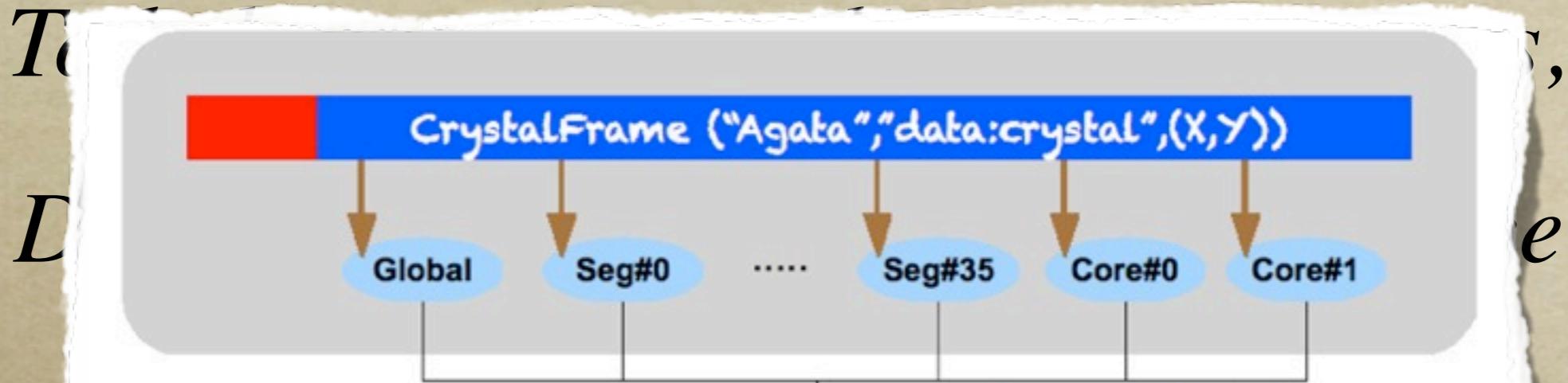


traces saved in
event_mezzdata.bdat

psa hits saved in
PSA_1R_XXX.adf

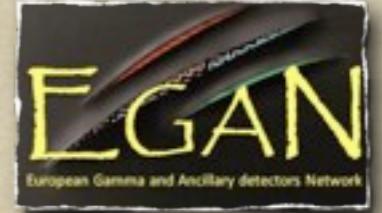
tracked γ saved in
Tracked_XXX.adf

The Data Interface





Frame has versions



Why version numbers ?

AGATA : 10 years project

- algorithms (Tracking, PSA) likely to change
- better to include this since the beginning

small modifications - float ↗ double

Version (Major, Minor)

large modifications - error on hits



Frame has versions



the full definition of circulating frames are in ADF.conf

...

```
Frame: Agata data:crystal 4 0 Agata data:crystal 65000 0
Frame: Agata data:ccrystal 4 0 Agata data:ccrystal 65000 0
Frame: Agata data:ranc0 4 0 Agata data:ranc0 65000 0
Frame: Agata data:ranc1 4 0 Agata data:ranc1 65000 0
Frame: Agata data:psa 4 0 Agata data:psa 65000 1
Frame: Agata data:tracked 4 0 Agata data:tracked 65000 0
Frame: Agata event:data 4 0 Agata event:data 4 0
Frame: Agata event:data:psa 4 0 Agata event:data:psa 4 0
Frame: Agata meta:vertex 4 0 Agata meta:vertex 0 1
```

...

Note : ADF.conf should be in the directory pointed by ADF_CONF_PATH



```
SharedFP * FrameTrigger::Add ( const FactoryItem & key_item,
                               const FactoryItem & frame_item,
                               bool           iscons = true,
                               const Char_t *   option = ""
                               )                           [virtual]
```

Add a frame to the list of required frames.

the frame is added with a flag to tell if the given frame is consumable or not i.e. if it is still on the output dataflow in case the trigger defines also an output frame. isconc true if

A FrameTrigger has a tree (stack) structure as followed :

```
MainFrame (#0)
SubFrame (#1)
SubFrame (#2)
...
```

The mainframe is mandatory, other ones (subframes inside the main one) are optional.

Options are :

- none (default) means one and exactly one such a kind of frame is expected to trig
- ! : anti coincidence means the current trigger does not contain the frame
- | : means the frame is there or not. In such case, check if the frame is there with IsIndividualFired

Implements ADF::DFTTrigger.

Reimplemented in ADF::AgataFrameTrigger.

Definition at line 594 of file Trigger.cpp.



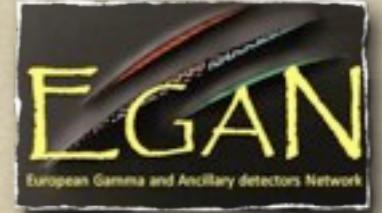
```
AgataFrameTrigger *trig =
    AgataFrameTrigger::Build("TRACKING", "event:data event:data:psa");
```



adf fill the frame for you, not the data interface



Overviews



Actor's actions

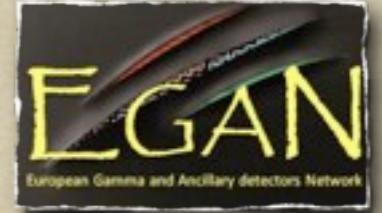
What already exists

Watchers

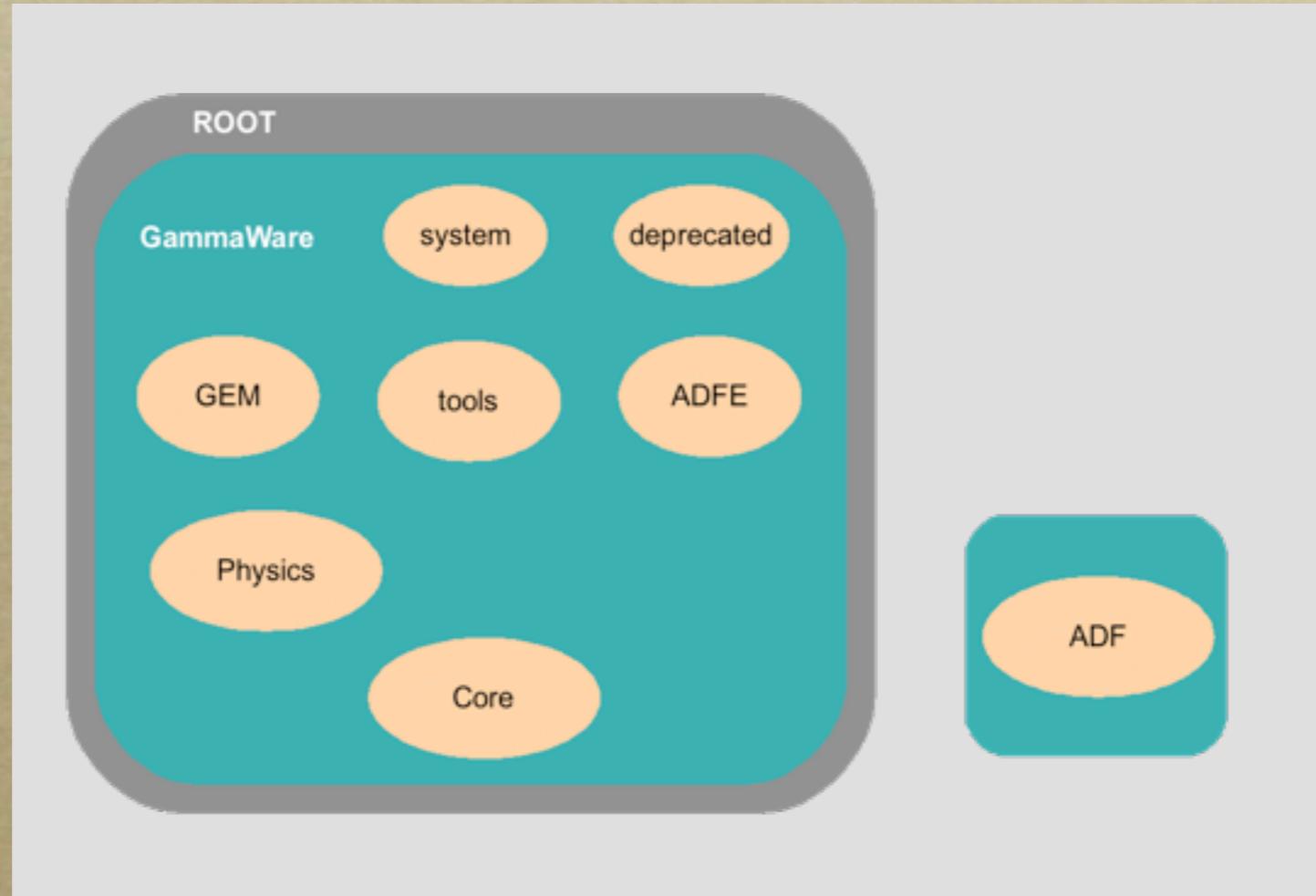
Data flow structure



GammaWare



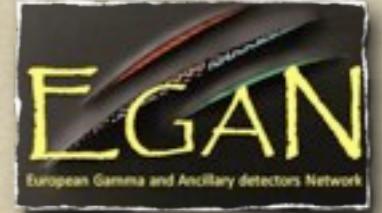
ROOT : huge framework for data analysis



Gw: libraries to add to root γ -ray like analysis



Watchers[Gw]



Def: task dedicated to a given Frame (Trigger)
idea : re-usable bricks

Ex of watchers :

on data:psa
task to display hits in 3D
on data:ranc1
display raw spectra
calibrate + do recoil velocity, make it available for other watchers
display recoil velocity
on data:tracked
 $\gamma\gamma$ matrix
write out in a root tree

Watchers[Gw]

Watchers can be linked in actors

```
...
FrameDispatcher *fd;
...
// a trigger on event with hits, tracked gammas and ancillary
AgataFrameTrigger *trig =
    AgataFrameTrigger::Build("TRACKING", "event:data event:data:psa data:tracked data:ranc1");

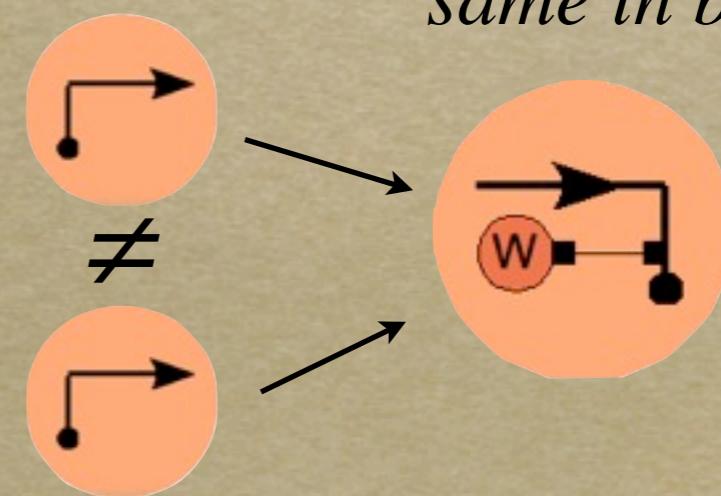
// set the main trigger to coincidences between ancillary et gammas
fd->SetTrigger(trig);

// specific to tracked frame
// gamma-gamma matrix
fd->Add<Coinc2D>(GetWN("GxG",ext),"Gamma Gamma coincidence");
...
...
```

...   ...

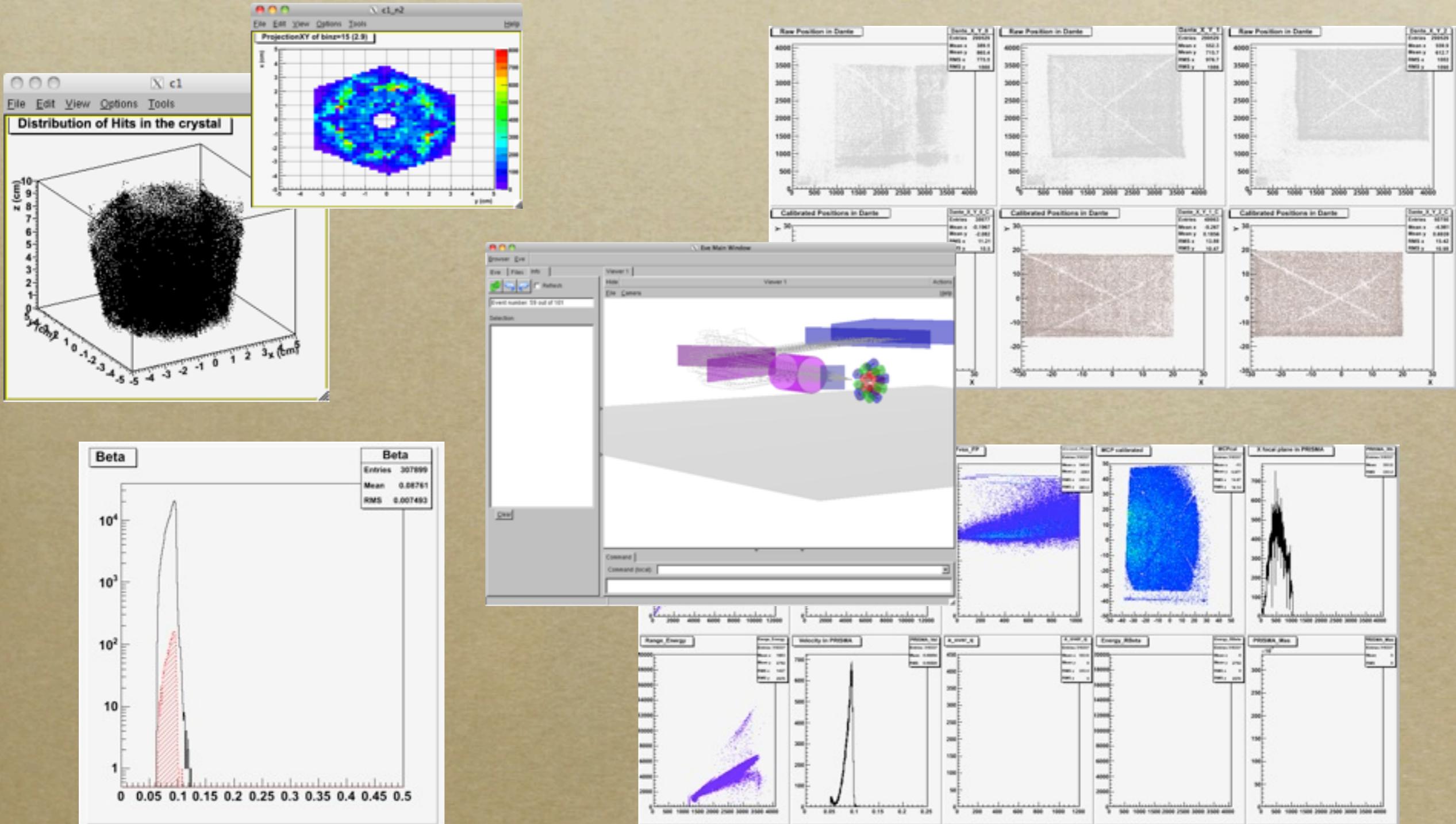
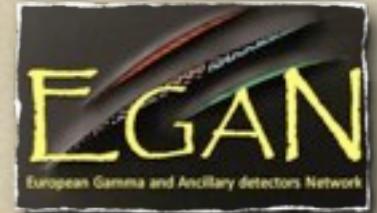
Online, get data from socket

Offline, get data from .adf files



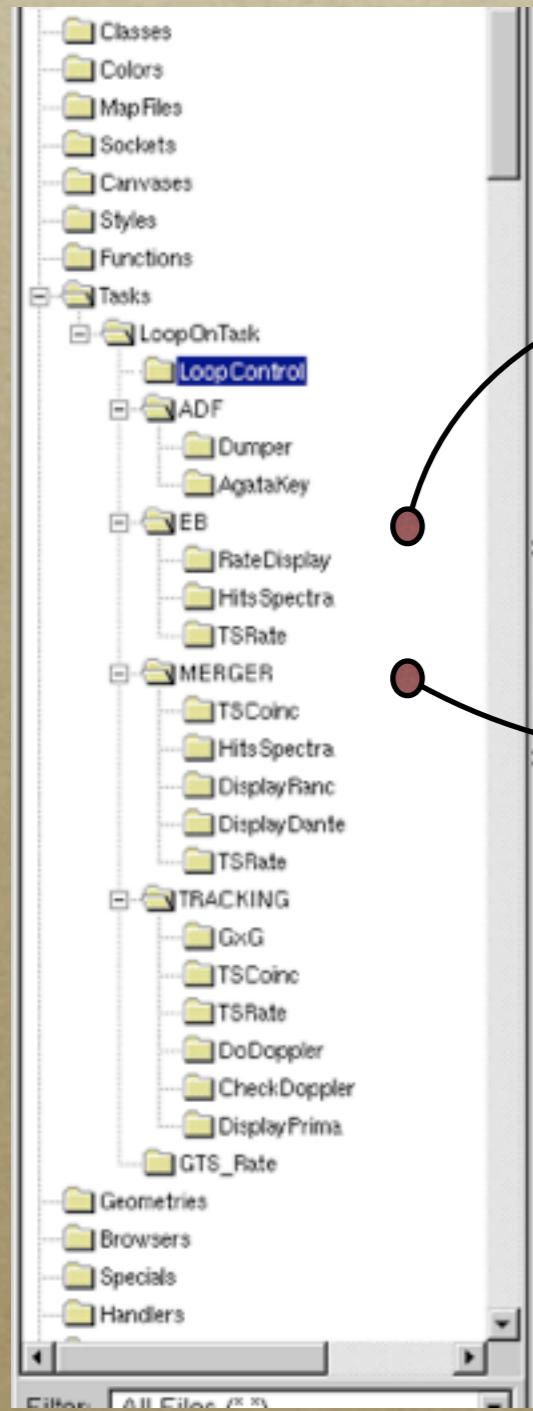
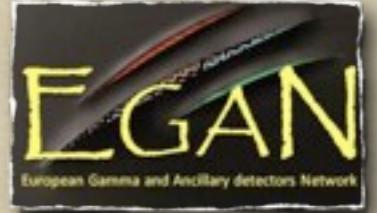


Watchers[Gw]



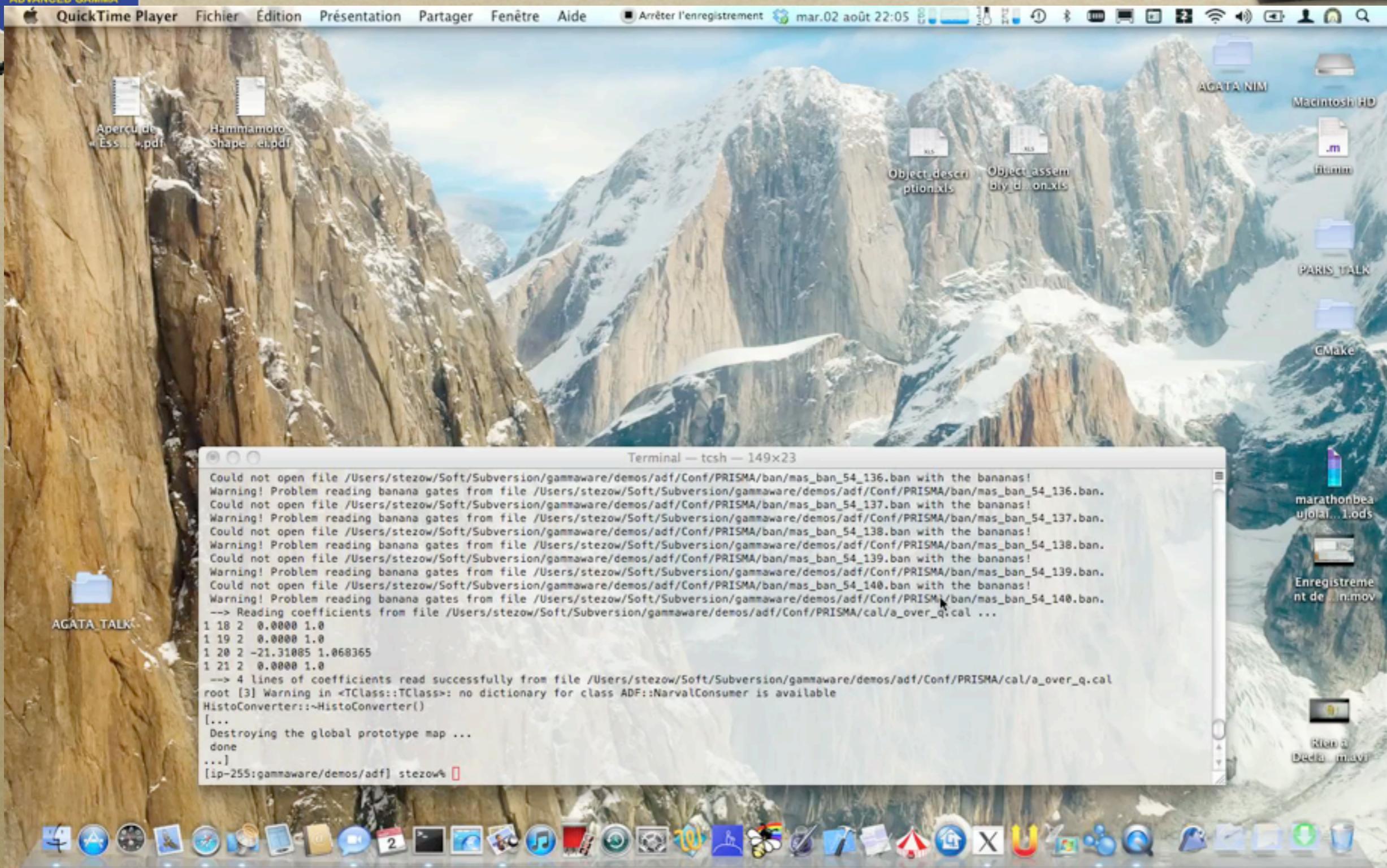
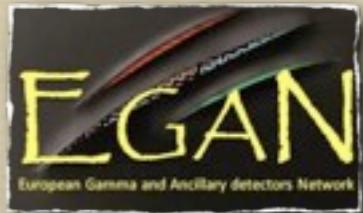


Watchers[Gw]



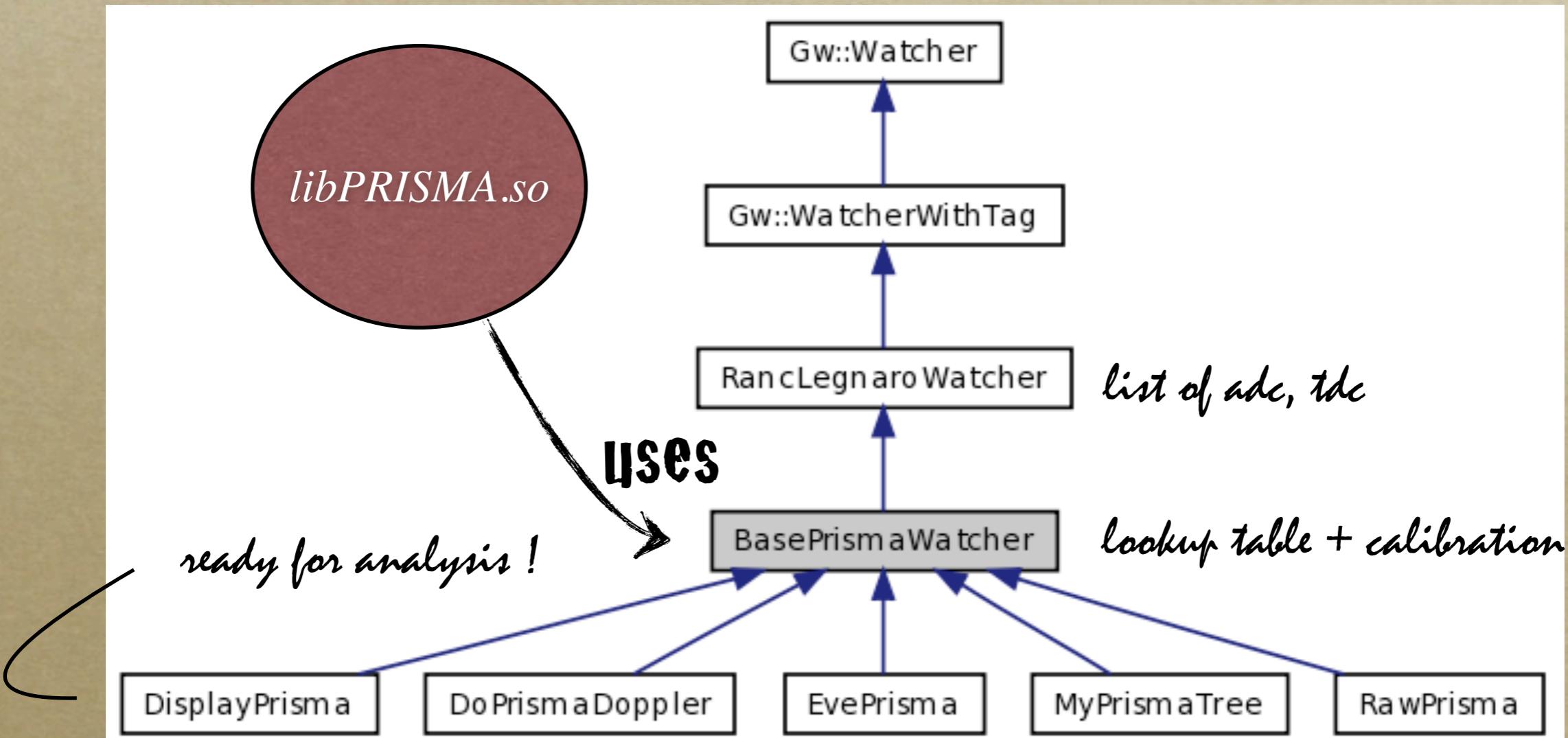


Online Watchers[Gw]



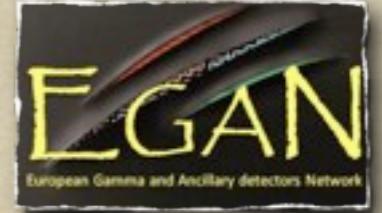
Watchers[Gw]

Inheritance : base class, service for daughter classes





Watchers[Gw]



constructor : build spectra

```
DisplayPrisma::DisplayPrisma(const char *name, const char *title): BasePrismaWatcher(name, title)
{
    IcABvsABCD      = new TH2F("Ic_ABvsABCD", "E_DeltaE_AB", 1024,0,12000,2048,0,8000);
    AddToPool(IcABvsABCD);
    IcAvsABCD      = new TH2F("Ic_AvsABCD", "E_DeltaE_A", 1024,0,12000,2048,0,8000);
    AddToPool(IcAvsABCD);
    TOF_D           = new TH2F("ToF(ns)vsX_FP(mm)", "ToFvsx_FP", 1024,0,1024,4096,0,4096);
    AddToPool(TOF_D);
    ...
}

void DisplayPrisma::Exec(Option_t *option)
{
    const double c_light = 29.97295 * cm/ns;

    // fill the array of floats and compute the PRISMA physics
    SetLastError(0u);
    BasePrismaWatcher::Exec(option);
    if (GetLastError() > 0)
        return;

    if (fPM->length() > 0. ) {
        Vector3D Vel = fPM->velocity()/c_light;

        IcABvsABCD   -> Fill(fPM->ic_energy(),fPM->ic_energy_AB_DE());
        TOF_D         -> Fill(fPM->x_fp() /mm, 10*fPM->tof()/ns);
        PRISMA_MCPcal -> Fill(fPM->mcp_x() /mm , fPM->mcp_y() /mm );
        PRISMA_X_FP   -> Fill( fPM->x_fp() /mm );
        PRISMA_Vel    -> Fill( Vel.rho() );
        Range_Energy->Fill(fPM->range(), fPM->ic_energy());
        Vel_Theta->Fill(10.*fPM->theta_c()/degree, Vel.rho());
        a_over_q->Fill(fPM->x_fp() /mm, fPM->a_over_q_uncal());
        Energy_RBeta->Fill(fPM->r_beta(), fPM->ic_energy());
        PRISMA_Mass->Fill(fPM->Mass());
    }
}
```

*just to allow global actions
(zero, save, delete ...)*

exec : fill spectra





Overviews



Basic elements

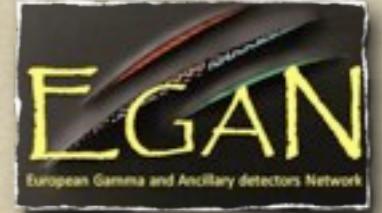
no standard analysis
→ *always new spectrum, cuts*
Improvement of existing actors
New actors (GSI) !

What already exists

How to extend .?



Overviews



New Watcher

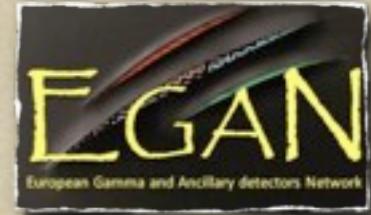
How to extend

About replay

New Actor



Add a new Watcher



Question : on what
→ give the

Ex : LaBr3 have been

- ancillary data
- base class is R
- create a class L
lookup table + calibration
- create a class for your analysis
 - built spectra
 - built TTree

```
void BaseLLaBr3Watcher::Exec(Option_t *option)
{
    void MyLLaBr3Tree::Exec(Option_t *option)
    {
        if ( gDebug > 3 )
            printf("MyLLaBr3Tree::Exec is called \n");

        // fill the array of floats and compute the PRISMA physics
        BaseLLaBr3Watcher::Exec(option);

        fNbLaBr3 = 0;
        for (Int_t i = 0u; i < fNumberOfModules; i++) {
            /*          if ( !fLaBr3[i].has_fired ) {
                        continue;
            } */

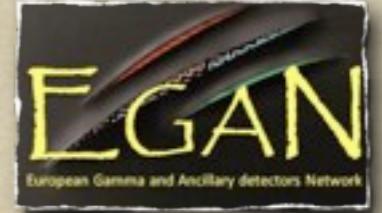
            fWhichLaBr3[fNbLaBr3] = i;
            fELaBr3[fNbLaBr3] = fLaBr3[i].E;
            fTLaBr3[fNbLaBr3] = fLaBr3[i].T;

            fNbLaBr3++;
        }

        // fill the tree only if this is the owner of the tree ... otherwise by
        TreeMaster
    }
}
```



Overviews



New Watcher

How to extend

About replay

New Actor



Add a new Filter



*As a filter, it inherits from NarvalFilter
(or other inheriting from it)*

You need to implement the :

process_config method

process_initialise method

read .conf file

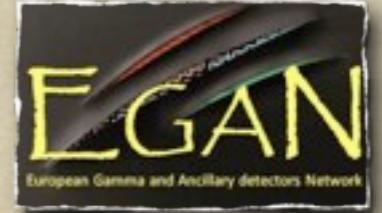
set the trigger

SetInput/Process/SetOutput method

Many examples + simple tracking soon in Gw



Overviews



New Watcher

How to extend

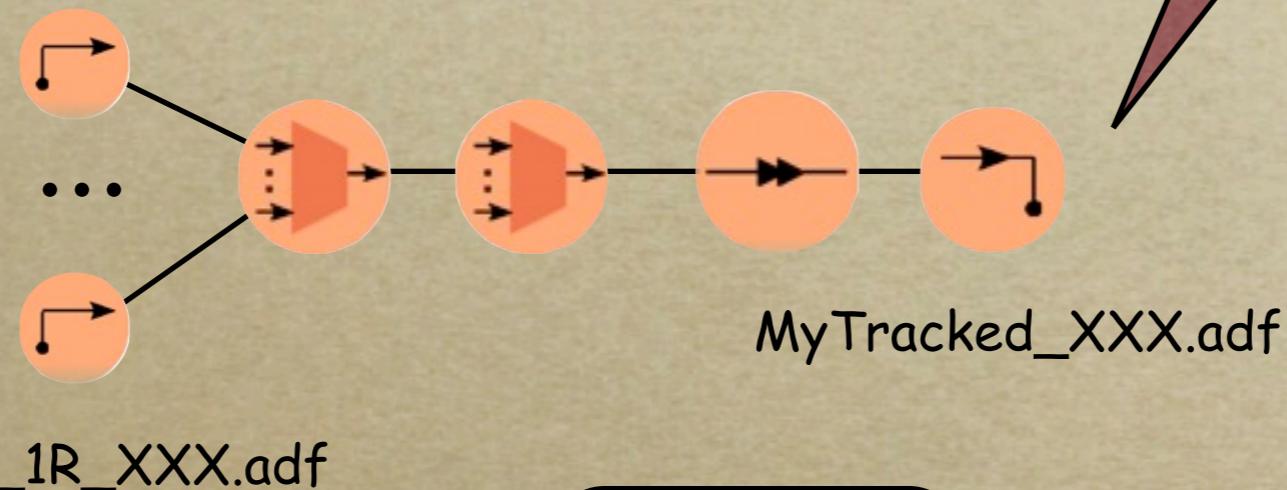
About replay

New Actor

Replay Tracking

*There are several possibilities
What is needed is PSA Hits*

1



femul

2

Tracked_XXX.adf

MyTracked_XXX.adf

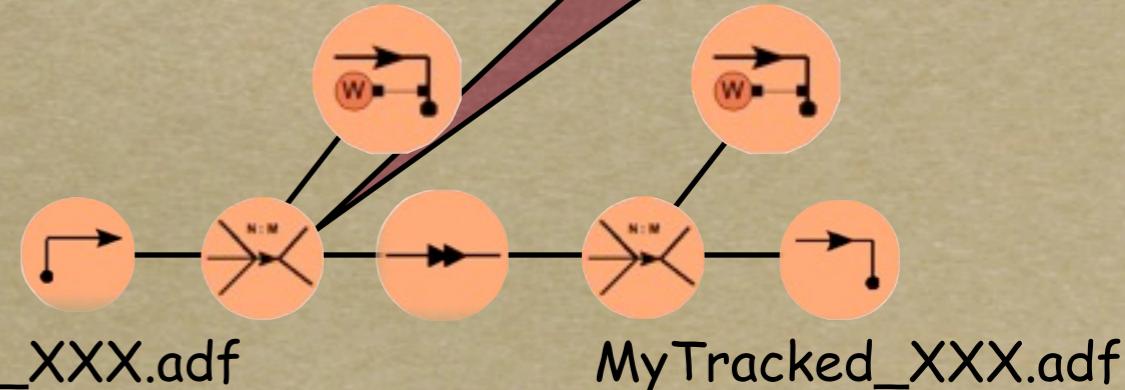
consume data:tracked, produce data:tracked

Tracked_XXX.adf

MyTracked_XXX.adf

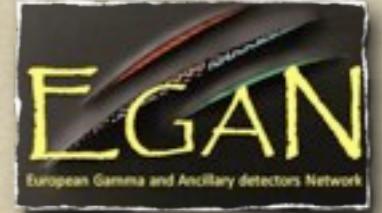
Gw

BasicReplica





About Replay



It depends from what to what !

*Tracking from hits (precedent slide) : femul, gw
Pb of Event builder / merger hits → end : femul*

From traces

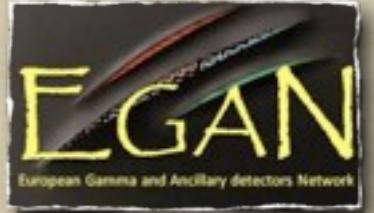
*one detector : femul, gw
all of them : Narval or femul (slow ...)*

Another ('future') solution : the GRID

tests have been done but not yet fully available for the community



About Replay



*GRID : resources (CPU/disk) available everywhere
backup*

T
(Legn)

*mainly tests so far :
have show gain in speed/time
still not in production level
code to be adapted
facilities for users to be developed
hope : for the coming year ...*

process

er2-3
(Strasbourg)

er2-3
(Valencia)

(IPN Lyon)